# STABILITY OF A SYSTEM OF PARALLEL BOILING CHANNELS

# V. I. Budnikov and A. V. Sergievskii

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The stability of the equilibrium steady-state regime is examined "in the small" for a system of parallel boiling channels connected to common headers. The necessary and sufficient conditions of stability are obtained.

A number of papers [1-3] have been devoted to the conditions of existence of instability in a system of parallel steam-generating channels. The present paper gives a solution of the problem of the stability of identical boiling channels, connected in parallel, the headers joining them, and the external parts of the network, - supply pipes, - (the "source") and a load (steampipes, turbines, condensers, etc.) (Fig. 1).

Neglecting the inertial properties of the external parts of the network, we may represent them as equivalent lumped resistances (inlet and outlet).



Fig. 1. Block diagram of the system of parallel boiling channels and the external parts of the network: 1), 2) equivalent lumped resistances (inlet and outlet). The pressure drop in the heated part of the channels (bc) will be considered negligibly small compared with that in the unheated parts (ab) and (cd). We shall represent parts (ab) and (cd) by equivalent lumped resistances.

The heated part of the channel is assumed to be long enough for the liquid heat-transfer agent, which arrives at the channel entrance at constant temperature, to be heated and evaporated and leave the channel in vapor form.

The system of dynamic equations of section (bc) will then consist of three groups, describing the dynamics of the economizer, evaporator, and superheater zones, and a system of boundary conditions determining the continuity of variation of the parameters of the heat-transfer agent as it passes from zone to zone.

We shall describe the dynamics of each zone by a system of heat balance and continuity equations

$$\frac{\partial}{\partial x} Gi + S \frac{\partial}{\partial t} \gamma i = Sq,$$

$$\frac{\partial}{\partial x} G + S \frac{\partial}{\partial t} \gamma = 0.$$
(1)

We shall also assume that the temperature of the external heater, the heat transfer coefficient, density and heat capacity of the liquid and vapor, and flow cross section of the heated part of the channels are constant, and that the heat capacity of the channel walls is negligibly small.

Let us examine one of the channels of the system. With the above assumptions, the dynamic equations of the heated section of the channel may be written as follows:

Economizer Zone

$$\frac{\partial}{\partial x} w_{l}i_{l} + \frac{\partial}{\partial t} i_{l} = \frac{k}{\gamma'} [\vartheta_{1} - \vartheta_{l}(x, t)],$$

$$0 \le x \le h_{ec}(t), w_{l}(t) = w_{in}(t), \ i_{l} = c \vartheta_{l},$$

$$i_{l}(0, t) = i_{in} = \text{const}, \ i_{l} [h_{ec}(t), t] = i_{s}(t).$$
(2)

Linearizing (2) [4] and using the Laplace transform method with zero initial conditions [5], we obtain

$$\overline{\Delta h}_{ec} = \left(\frac{di_s}{dp_2}\right)_0 \frac{\omega_{in,o} \gamma'}{k(\vartheta_1 - \vartheta_s)_0} \overline{\Delta p}_2 + \frac{1}{\lambda} (1 - \exp(-\lambda \tau_{ec})) \overline{\Delta \omega}_{in},$$
(3)

where  $\tau_{ec} = \frac{c\gamma'}{k} \ln \frac{\vartheta_1 - \vartheta_{in}}{\vartheta_1 - \vartheta_{s0}}$  is the time taken by the heat transfer agent to pass through the economizer zone. Evaporator Zone

$$\frac{\partial}{\partial x} \left[ w_{\mathbf{v}} \mathbf{\gamma}'' \varphi \, i_{\mathbf{v}} + w_{\mathbf{l}} \, \mathbf{\gamma}' \, (1 - \varphi) i_{\mathbf{s}} \right] + \frac{\partial}{\partial t} \left[ \mathbf{\gamma}'' \varphi \, i_{\mathbf{v}} + \mathbf{\gamma}' (1 - \varphi) \, i_{\mathbf{s}} \right] = q,$$

$$\frac{\partial}{\partial x} \left[ w_{\mathbf{v}} \mathbf{\gamma}'' \varphi + w_{\mathbf{l}} \, \mathbf{\gamma}' (1 - \varphi) \right] + \frac{\partial}{\partial t} \left[ \mathbf{\gamma}'' \varphi + \mathbf{\gamma}' \, (1 - \varphi) \right] = 0, \qquad (4)$$

$$w_{\mathbf{l}} \left[ h_{\mathbf{ev}}(t), t \right] = w_{\mathbf{in}}, \ w_{\mathbf{v}} = w_{\mathbf{v}} (w_{\mathbf{l}}, \ p_{\mathbf{2}}, \ \varphi, \ \dots), \ q = k \left[ \vartheta_{1} - \vartheta_{\mathbf{s}} \left( t \right) \right],$$

$$\varphi \left[ h_{\mathbf{ec}}(t), t \right] = 0, \ \varphi \left[ h_{\mathbf{ev}}(t), t \right] = 1, \ h_{\mathbf{ec}}(t) \leq x \leq h_{\mathbf{ev}}(t).$$

The state of the flow of heat transfer agent in the evaporator zone will be characterized by the mean volume steam content for the zone  $\varphi_{\text{mo}}$ , determined from (4) for the conditions of the initial equilibrium steady-state regime ( $\varphi_{\text{mo}}$  = const). Integrating (4) with respect to x over the interval  $h_{ec}(t) \le x \le h_{ev}(t)$ , linearizing the resulting equation, going over to Laplace transform variables with zero initial conditions, and taking (3) into account, we finally obtain

$$\frac{\overline{\Delta w}_{v}(h_{ev})}{w_{v0}} = -L_{1}(\lambda) \overline{\Delta p}_{2} + L_{2}(\lambda) \frac{\overline{\Delta w}_{in}}{w_{in,o}},$$
(5)

where

$$L_{1}(\lambda) = \frac{B(1-\sigma)\lambda\tau_{1}}{1+\lambda\tau_{1}} [\lambda\tau_{1}(1+A) + \psi].$$

$$L_{2}(\lambda) = \sigma + \frac{(1-\sigma)\exp(-\lambda\tau_{ec})}{1+\lambda\tau_{1}},$$

$$A = \sigma \frac{\varphi_{mo}}{1-\varphi_{mo}} \left(\frac{di_{v}}{di_{s}}\right)_{0}, \quad B = \left(\frac{di_{s}}{dp_{2}}\right)_{0}\frac{1}{r},$$

$$\tau_{1} = \frac{(1-\varphi_{mo})\gamma'r}{k(\vartheta_{1}-\vartheta_{s})_{0}},$$

$$\psi = \frac{1}{1-\varphi_{mo}} \left[\varphi_{mo} + (1-\varphi_{mo})\left(\frac{di_{v}}{di_{s}}\right)_{0}\right], \quad \sigma = \frac{\gamma''}{\gamma'}$$

Replacing  $\overline{\Delta w}_{v}(h_{ev})$  by  $\overline{\Delta w}_{v}(H) = \overline{\Delta w}_{ex}$  in (5) (the validity of this substitution follows from the assumed constant density of the vapor in the part of the superheater zone  $h_{ev}(t) \leq x \leq H$ ) we obtain the dynamic equation of the heated section of the boiling channel:

$$\frac{\overline{\Delta w}_{\text{ex}}(H)}{w_{\text{ex},o}} = -L_1(\lambda) \overline{\Delta p}_2 + L_2(\lambda) \frac{\overline{\Delta w}_{\text{in}}}{w_{\text{in},o}}.$$
(6)

The linearized hydraulic equations of the unheated sections of the channels, the source, and the load have the form

$$\overline{\Delta p_1} - \overline{\Delta p_3} = \frac{2}{N} \left[ \sum_{j=1}^{N} U_{1j} \frac{\overline{\Delta w_{\text{in},j}}}{(w_{\text{in},j})_0} + \sum_{j=1}^{N} U_{2j} \frac{\overline{\Delta w}_{\text{ex},j}}{(w_{\text{ex},j})_0} \right],$$

$$\overline{\Delta p_{2j}} = \overline{\Delta p_1} - 2U_{1j} \frac{\overline{\Delta w_{\text{in},j}}}{(w_{\text{in},j})_0},$$
(7)

$$-\overline{\Delta p_1} = \frac{2V_1}{N^3} \sum_{j=1}^{N} \frac{\overline{\Delta w_{\text{in},j}}}{(w_{\text{in},j})_0},$$
(8)

206

where

$$\begin{split} \Delta p_{3} &= \frac{1}{N^{3}} \sum_{j=1}^{N} \frac{1}{(w_{\text{ ex.},j})_{0}}, \\ V_{1} &= -\frac{1}{2} G_{0}^{*} \left(\frac{\partial p_{1}}{\partial G^{*}}\right)_{0}, \quad V_{2} &= -\frac{1}{2} G_{0}^{*} \left(\frac{\partial p_{3}}{\partial G^{*}}\right)_{0}, \\ U_{1j} &= \frac{1}{2} G_{j 0} \left[\frac{\partial (p_{1} - p_{2j})}{\partial G_{j}}\right]_{0}, \quad U_{2j} &= -\frac{1}{2} G_{j 0} \left[\frac{\partial (p_{2j} - p_{3})}{\partial G_{j}}\right]_{0}, \\ G_{0}^{*} &= \sum_{j=1}^{N} G_{j 0}, \quad j = 1, 2, 3, \dots, N. \end{split}$$

 $2V_2 \quad \mathbf{\nabla} \quad \overline{\Delta w}_{ex}$ 

If the heat transfer agent reaches the inlet header through a pipe connected to the main in which the pressure  $p_0 = = const$  and if this pipe, the unheated sections of the channels, and the load are turbulent resistances (turbulent self-similar flow regime), then  $V_1 = (p_0 - p_1)_0$ ,  $V_2 = (p_3 - p_4)_0$ ,  $U_{1j} = (p_1 - p_{2j})_0$ ,  $U_{2j} = (p_{2j} - p_3)_0$ , where  $(p_3 - p_4)_0$  is the steady-state pressure drop at the load.

## Characteristic Equation. Stability.

The hydraulic characteristics of the unheated sections (ab) and (cd) and the  $\vartheta_{1j}$  will be assumed to be identical for all N channels. Then the mass flow of the heat transfer agent, the length of the zones, and the values of all the other parameters characterizing the equilibrium steady-state regime will not depend on the channel number j. In this case the characteristic equation of system (6-9) will have the form

$$(F_1)^{N-1} F_2 = 0,$$
  
$$F_m = 2L_1 \Phi_{1m} + L_2 \Phi_{2m} + \Phi_{1m},$$

where

$$m = 1,2; \ \Phi_{11} = U_1, \ \Phi_{21} = U_2,$$
  
$$\Phi_{12} = \frac{V_1}{N^2} + U_1, \quad \Phi_{22} = \frac{V_2}{N^2} + U_2,$$

 $F_1$  determines the stability of the system ("in the small") in relation to so-called interchannel (inter-loop) pulsation, and  $F_2$  in relation to general boiler pulsation<sup>\*</sup>. It is thus necessary and sufficient for the stability of the system under examination to achieve stability with respect to both types of possible pulsations: interchannel and general boiler.

Since the operators  $F_1$  and  $F_2$  differ only in the values of the parameters, to determine the conditions of steadycorrection made has created more space below insert 303 e directly above. Please redistribute this space.

$$2L_1\Phi_1\Phi_2 + L_2\Phi_2 + \Phi_1 = 0. \tag{10}$$

Carrying out a D-partition [6-7] of the plane of the parameters  $\Phi_2$  and  $\Phi_1$ , we find that all the roots of (10) have a negative real part if  $\Phi_2$  and  $\Phi_1$  lie in region D<sub>0</sub>, located in the first quadrant of the ( $\Phi_2$ ,  $\Phi_1$ ) plane, and above the curve determined by the following equations:

$$\Phi_{2} = (\sin \omega \tau_{ec} + \omega \tau_{1} \cos \omega \tau_{ec}) \times \times [2B \omega \tau_{1} \{(1 - \sigma) \omega \tau_{1} (1 + A) \sin \omega \tau_{ec} - \sigma [\psi + (\omega \tau_{1})^{2} (1 + A)] - (1 - \sigma) \psi \cos \omega \tau_{ec} \}]^{-1}, \qquad (11)$$

$$\Phi_{1} = \frac{\sin \omega \tau_{ec} + \omega \tau_{1} \cos \omega \tau_{ec}}{2B \omega \tau_{1} [\psi + (\omega \tau_{1})^{2} (1 + A)]}, \quad \frac{\pi}{2} \leq \omega \tau_{ec} \leq \pi.$$

\*In the case of general boiler pulsation, fluctuations in the mass flow of heat transfer agent occur synchronously in the individual channels. "Interchannel" pulsation is characterized by constant mass flow of heat transfer agent through the source and load and asynchronous fluctuations in the individual channels. It is therefore necessary and sufficient for the stability of the system that points ( $\Phi_{21}$ ,  $\Phi_{11}$ ) and ( $\Phi_{22}$ ,  $\Phi_{12}$ ) belong to the region D<sub>0</sub>, i.e.,

$$(\Phi_{21}, \Phi_{11}), (\Phi_{22}, \Phi_{12}) \in D_0.$$
 (12)

When N = 1,  $(F_1)^{N-1} \equiv 1$ , so the stability condition for a single channel has the form

$$(\Phi_{22}, \Phi_{12}) \in D_0.$$

It follows from (12) that

1) the stability of the equilibrium steady-state regime depends appreciably on the hydraulic characteristics of the channels, their number, and the characteristics of the external parts of the network;



· Fig. 2. Boundary of stability region D<sub>0</sub>: a) for  $\varphi_{mo} = 0.85 (1, 2, 3, 4 - \vartheta_i = 512, 472, 432, 392°K, respectively);$ b) for  $\vartheta_{in} = 472^{\circ} K (1, 2, 3, 4, 5 - \varphi_{mo} = 0, 09, 0, 47, 0, 65, 0, 85, 1 respectively).$ 

2) the stability of the system with respect to interchannel pulsations is not, in general, determined by its stability with respect to general boiler pulsations (the special case of  $V_2 = 0$  examined in [3] is an exception);

3) there is a critical value of the parameter  $U_1^* = U_1^*$   $(p_{20}, i_{1n}, k, \vartheta_1)$ , such that for all  $U_1 > U_1^*$ , the system will be stable for any N,  $V_1$ ,  $V_2$  and  $U_2$ ;

4) the period of the oscillations developing in the system on passing through the boundary of the stability region (11) is of the same order as the time taken by the heat transfer agent to pass through the economizer zone.

The location of the boundary of the stability region  $D_0$  for the case in which the heat transfer agent is water at



Fig. 3. Variants of the relative location of line segment (13) and curve (11) -1, 2, 3a, 3b, 4.

 $p_{20} = 3.92 \text{ Mn/m}^2$  and q = const, is shown in Fig. 2.

The results of similar calculations show that for other values of the pressure  $p_{20}$  (0.28  $\leq p_{20} \leq 9.8$  Mn/m<sup>2</sup>) the shape of the region  $D_0$  and the dependence of the location of its boundary on  $\varphi_{mo}$  and  $\vartheta_i$  are qualitatively similar to those in Fig. 2.

The dependence of the stability of the system on the number of channels is of interest. Let us take an example. Assume that  $V_1$  and  $V_2$  do not depend on N. For  $V_1 = (p_0 - p_0)$  $-p_1$ <sub>0</sub> and  $V_2 = (p_3 - p_4)_0$  the condition  $V_1 = \text{const}$ ,  $V_2 =$ = const indicates that, as the number of channels changes, the hydraulic characteristics of the supply line and load also change, in such a way that the steady-state pressure

drops 
$$(p_0 - p_1)_0$$
,  $(p_3 - p_4)_0$  and the quantities  $p_0$  and  $p_4$  remain unchanged. Note that for  $V_1 = \text{const}$  and  $V_2 = \text{const}$   
$$\lim_{N \to \infty} \Phi_{22}(N) = \Phi_{22}(\infty) = \Phi_{21}, \quad \lim_{N \to \infty} \Phi_{12}(N) = \Phi_{12}(\infty) = \Phi_{11}.$$

Hence the conditions of stability of the steady-state regime may be written in the form \*

$$[\Phi_{22}(N), \Phi_{12}(N)] \in D_0, [\Phi_{22}(\infty), \Phi_{12}(\infty)] \in D_0.$$

<sup>\*</sup>As was pointed out, for N = 1 the stability condition may be written  $[\Phi_{22}(1), \Phi_{12}(1)] \in D_0$ .

When N varies from 1 to infinity, the points  $[\Phi_{22}(N), \Phi_{12}(N)]$  lie on the line segment:

$$\Phi_{1} = \frac{V_{1}}{V_{2}} \Phi_{2} + \Phi_{12}(\infty) - \frac{V_{1}}{V_{2}} \Phi_{22}(\infty).$$

$$\Phi_{22}(\infty) \leq \Phi_{2} \leq V_{2} + \Phi_{22}(\infty).$$
(13)

Depending on the relative location of segment (13) and curve (11) in the plane ( $\phi_2$ ,  $\phi_1$ ), the following possibilities, in particular, may be realized (see Fig. 3):

1) If segment (13) lies entirely above curve (11), the system is stable for any N.

2) If segment (13) lies entirely below curve (11), the system is unstable for any N.

3) Segment (13) intersects curve (11) once. Then:

a) if the right end of the intercept lies below the curve, a number  $m_1$  exists such that, for all N >  $m_1$ , the system is stable, but it is unstable for N <  $m_1$  (for N <  $m_1$  the stability condition with respect to general boiler pulsations is disturbed, but the system remains stable in the small with respect to interchannel pulsations);

b) if the left end of the intercept lies below the curve, then for N = 1 the system is stable, but it is unstable for  $N \ge 2$  (for  $N \ge 2$  the stability condition with respect to interchannel pulsations is disturbed; the system may be stable with respect to general boiler pulsations).

4) If segment (13) cuts curve (11) twice, the system is either stable for any N, or numbers  $m_2$  and  $m_3$  exist, such that for  $m_2 < N < m_3$  the system is unstable, and for  $N < m_2$  and  $N > m_3$  it is stable (for  $m_2 < N < m_3$  the stability condition with respect to general boiler pulsations is disturbed).

#### NOTATION

 $p_1$ ,  $p_2$ , and  $p_3$  - pressure at header inlet, in heated part of channel, and at header outlet; G - mass flow rate of heat transfer agent;  $p_1(G^*)$  and  $p_3(G^*)$  - functions determining the dependence of pressure in the headers on the mass flow rate of heat transfer agent in sections 1 and 2, respectively; j - number of boiling channel; w - velocity of heat transfer agent;  $\gamma$  - density of heat transfer agent;  $\gamma'$  - density of liquid;  $\gamma''$  - density of vapor; q - heat flux to unit volume of heat transfer agent; c - heat capacity of liquid;  $\vartheta_1$  - temperature of external heater;  $\vartheta_1$  and  $\vartheta_s$  - temperature of heat transfer agent at channel inlet and at saturation line; i - enthalpy;  $\Delta$  - deviation of a variable from its steady-state value;  $\varphi$  - fraction of flow cross section occupied by vapor;  $\varphi_{\rm mo}$  - mean volume steam content over evaporation zone; S - cross section of channel; x - coordinate calculated from beginning of heated section;  $h_{\rm ec}$  - coordinate of boundary between economizer and evaporator zones;  $h_{\rm ev}$  - coordinate of boundary between evaporator and superheater er zones; H - length of heated section of channel; t - time;  $\lambda$  - Laplace transform parameter. Subscripts: 0 - refers to values of variables in the equilibrium steady-state regime in the neighborhood of which linearization is carried out; l - liquid heat transfer agent; v - vapor; in - inlet; ex - outlet.

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Engineering Physics Institute, Gor'kii